

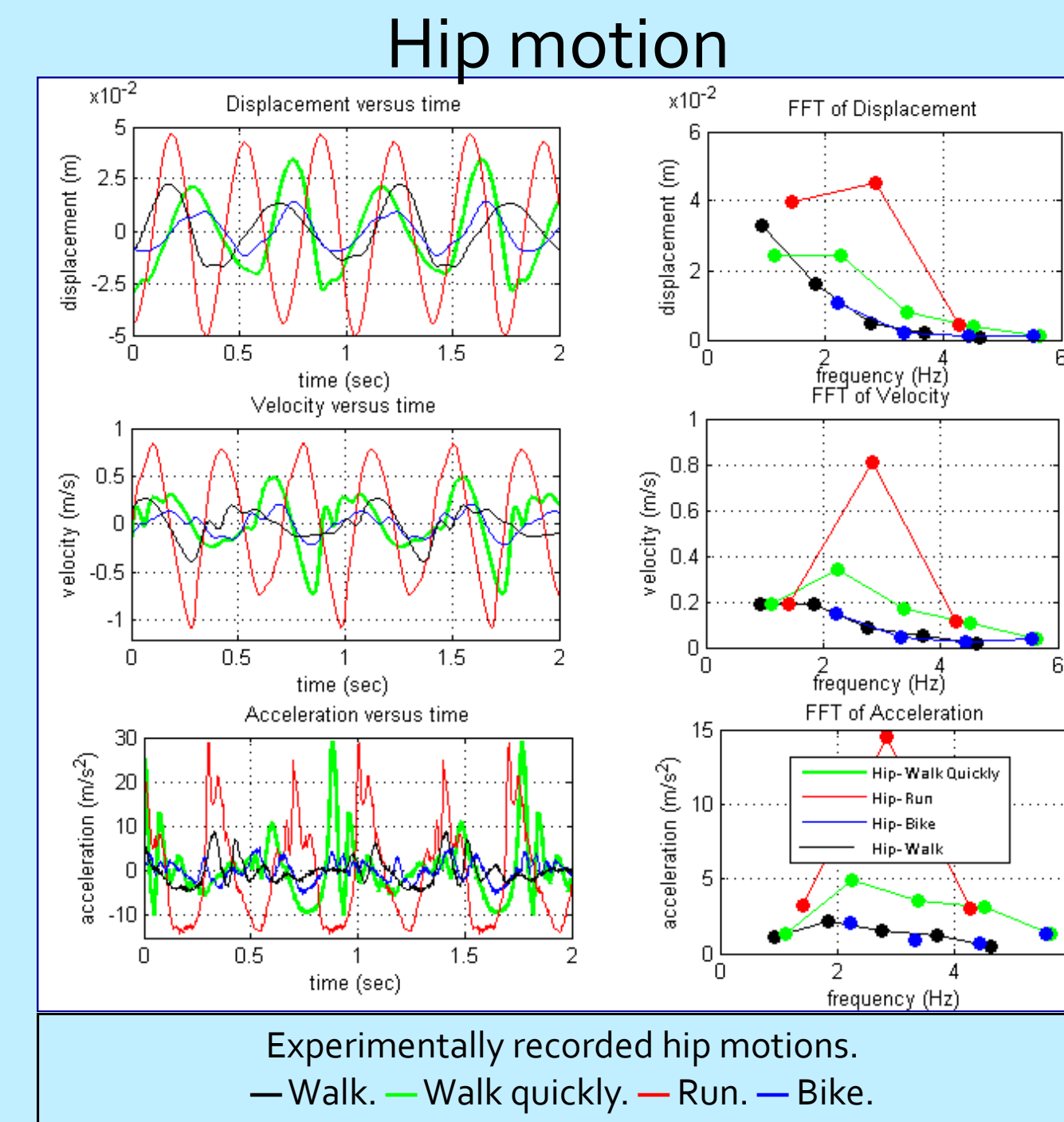
Challenge

- Ambient vibrations are stochastic, multi-frequency, and time-varying
- Traditional linear oscillators can only absorb ambient energy at one frequency
- Example scenarios:
 - Ambient vibration energy harvesting
 - Cell phones carried by people
 - Ocean wave utility-scale generators
 - Small electronics in remote locations
 - MEMs sensors implanted in the body
 - Shock absorption
 - Protect offshore platforms from water wave impacts
 - Protect buildings from earthquakes

Solution

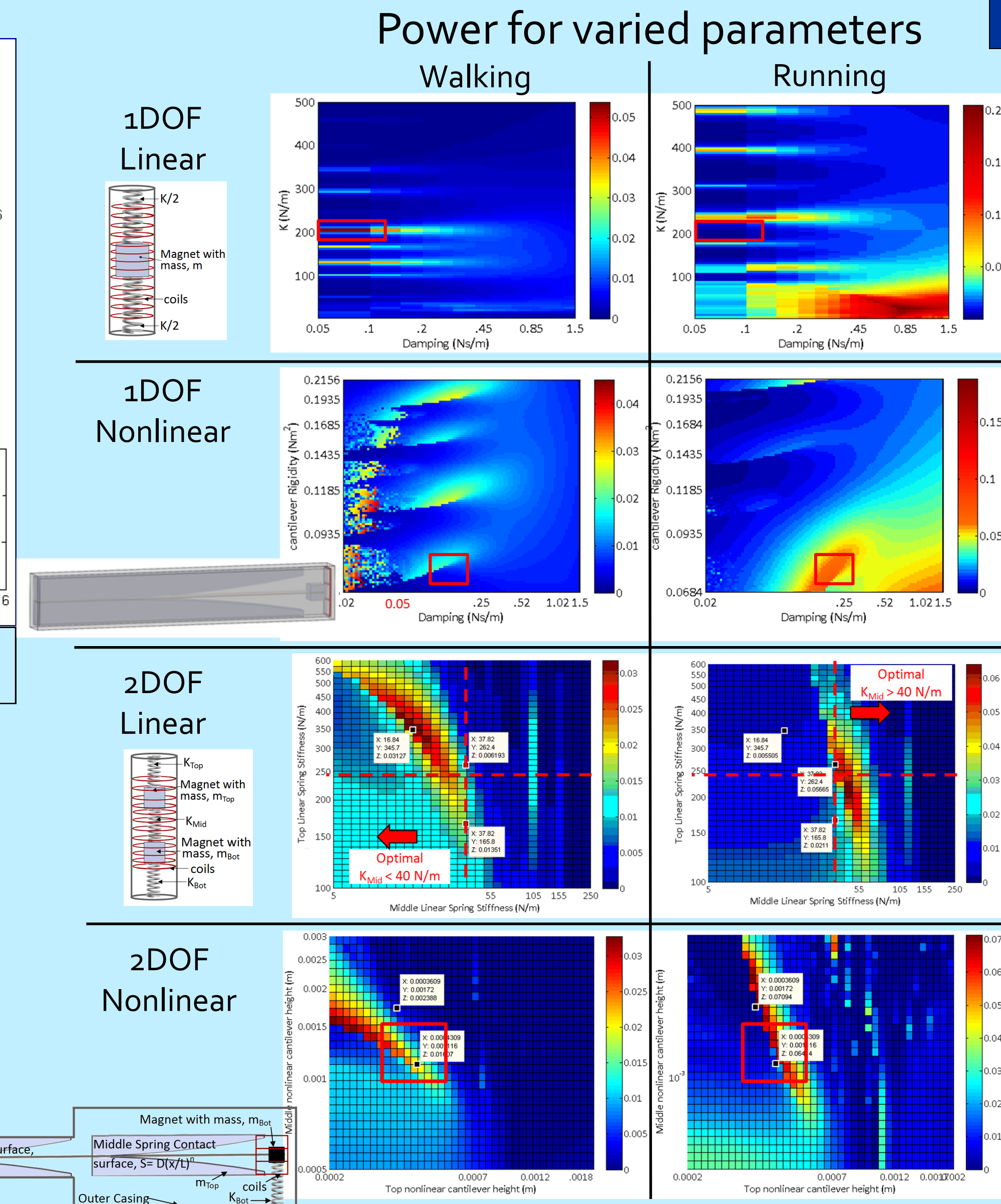
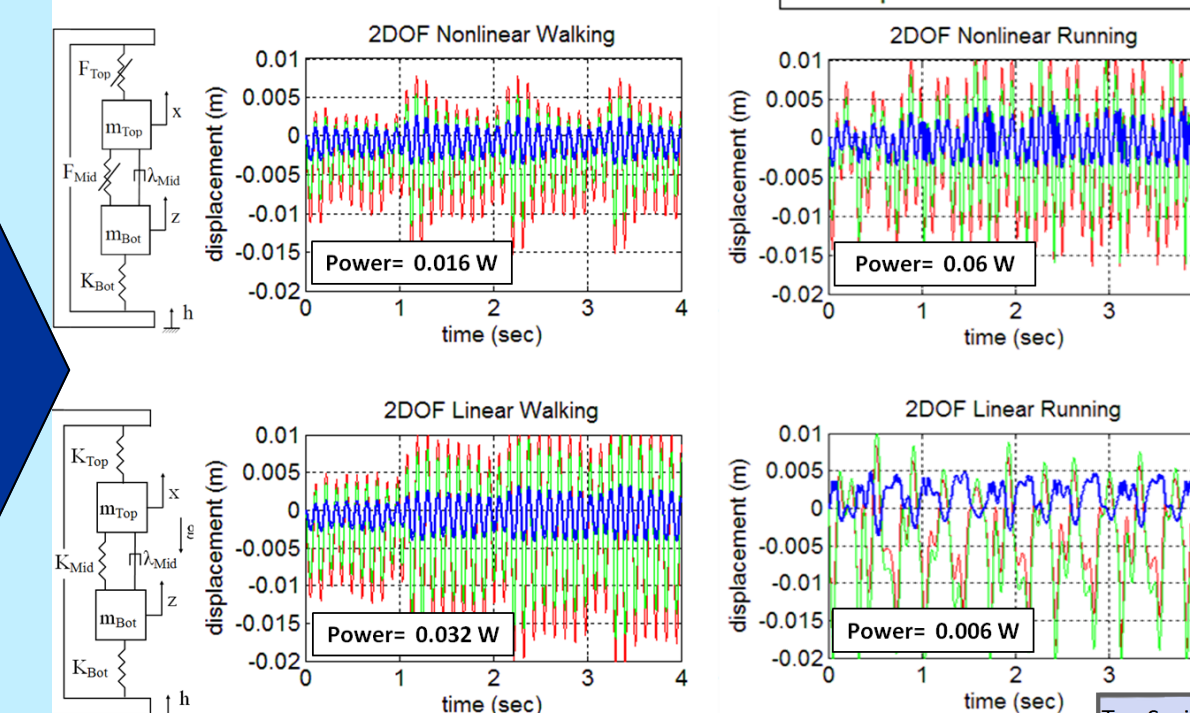
- Nonlinear oscillators are more robust to vibration signal changes than linear systems
 - Passive solution (versus using controls)

Case Study: Power a cell phone from a person walking



Comparison of 2DOF Nonlinear and 2DOF Linear Dynamics

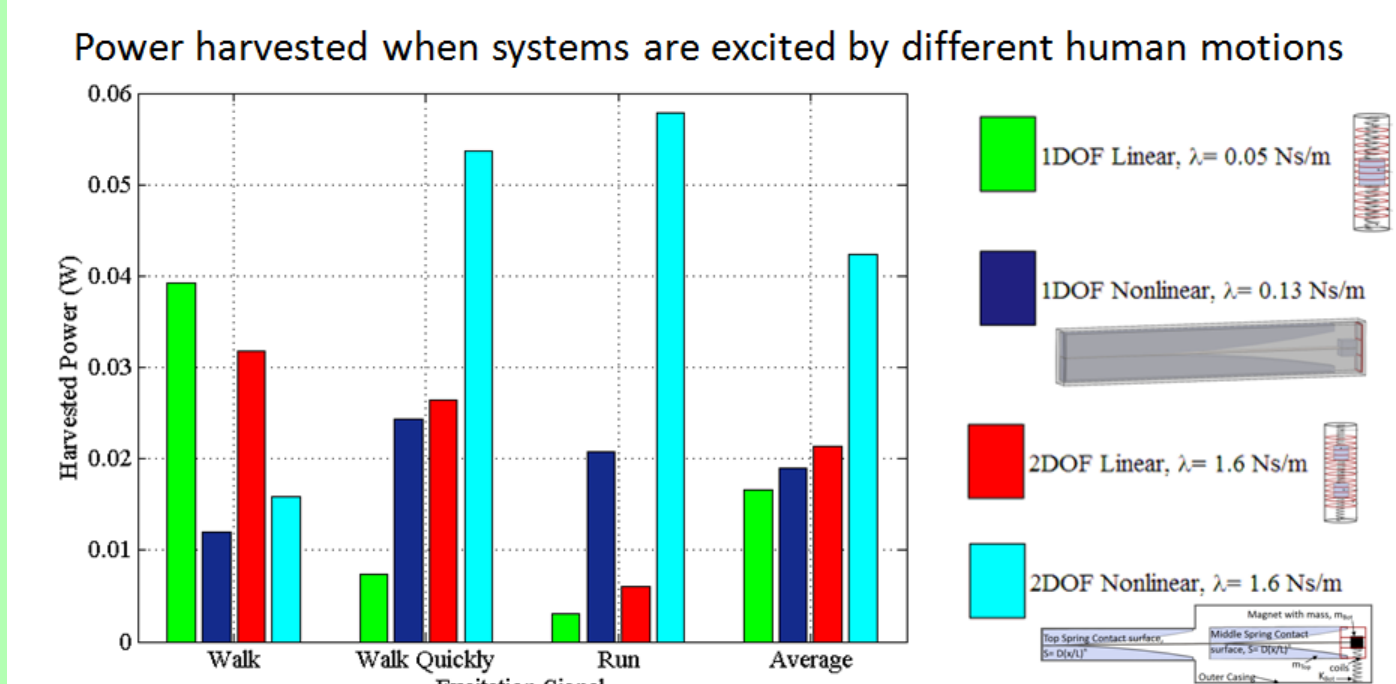
- Both systems: $\lambda_{Mid} = 1.6 \text{ Ns/m}$
- Power = $\lambda_{Mid}(\dot{X} - \dot{Z})^2 \sim \lambda_{Mid}(\dot{a}\omega)^2$



Conclusions

- Nonlinearity makes the system more robust to environmental vibration spectrum changes

System performance comparison



Common constraints:

- Total mass: 60 g
- Total device height: 6.8 cm

Systems optimized for maximum average power

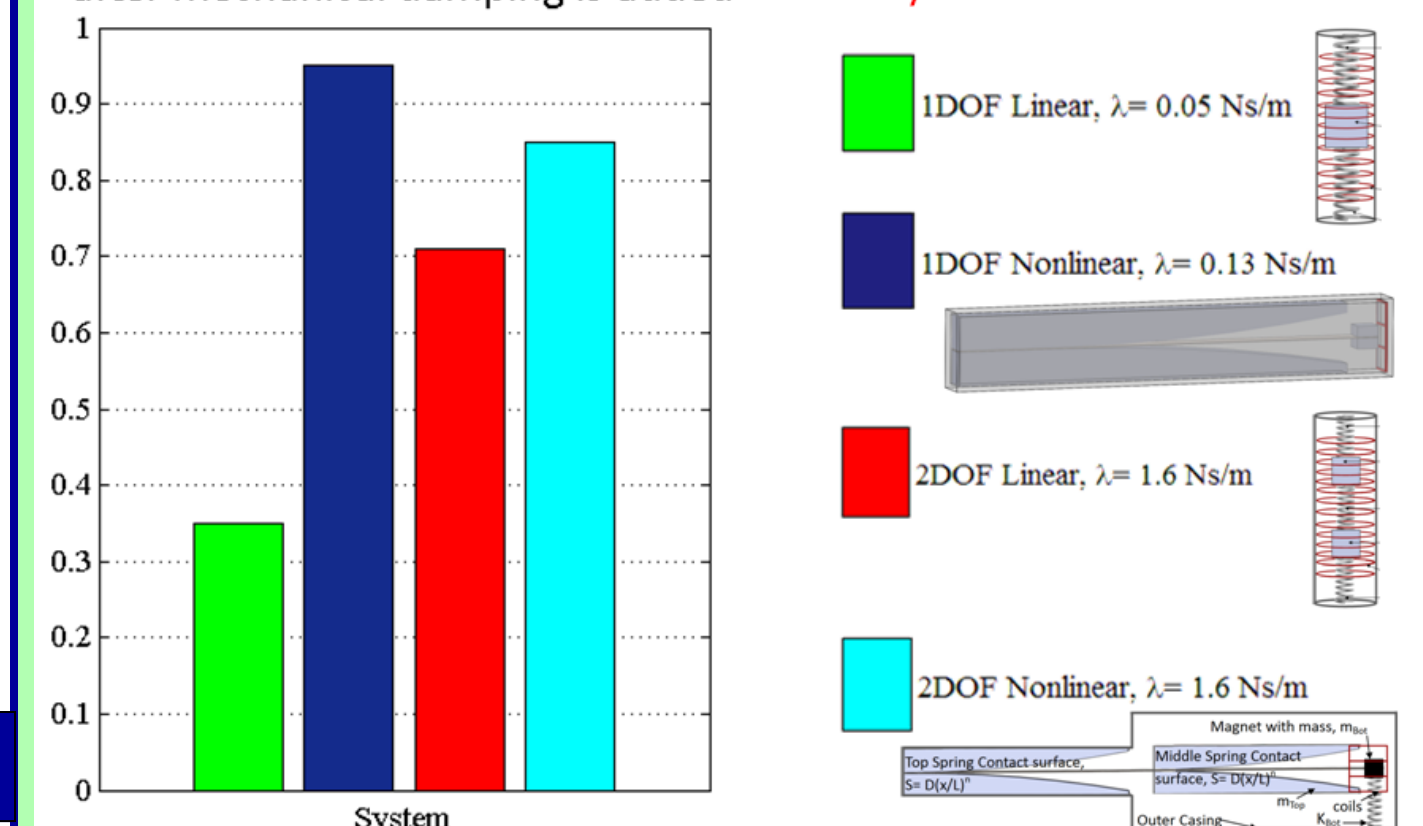
- Constraint: non-negligible amount of harvested power during walking

- Nonlinear systems are also more robust to parasitic damping

Robustness to Parasitic Damping

Fraction of power harvested after mechanical damping is added

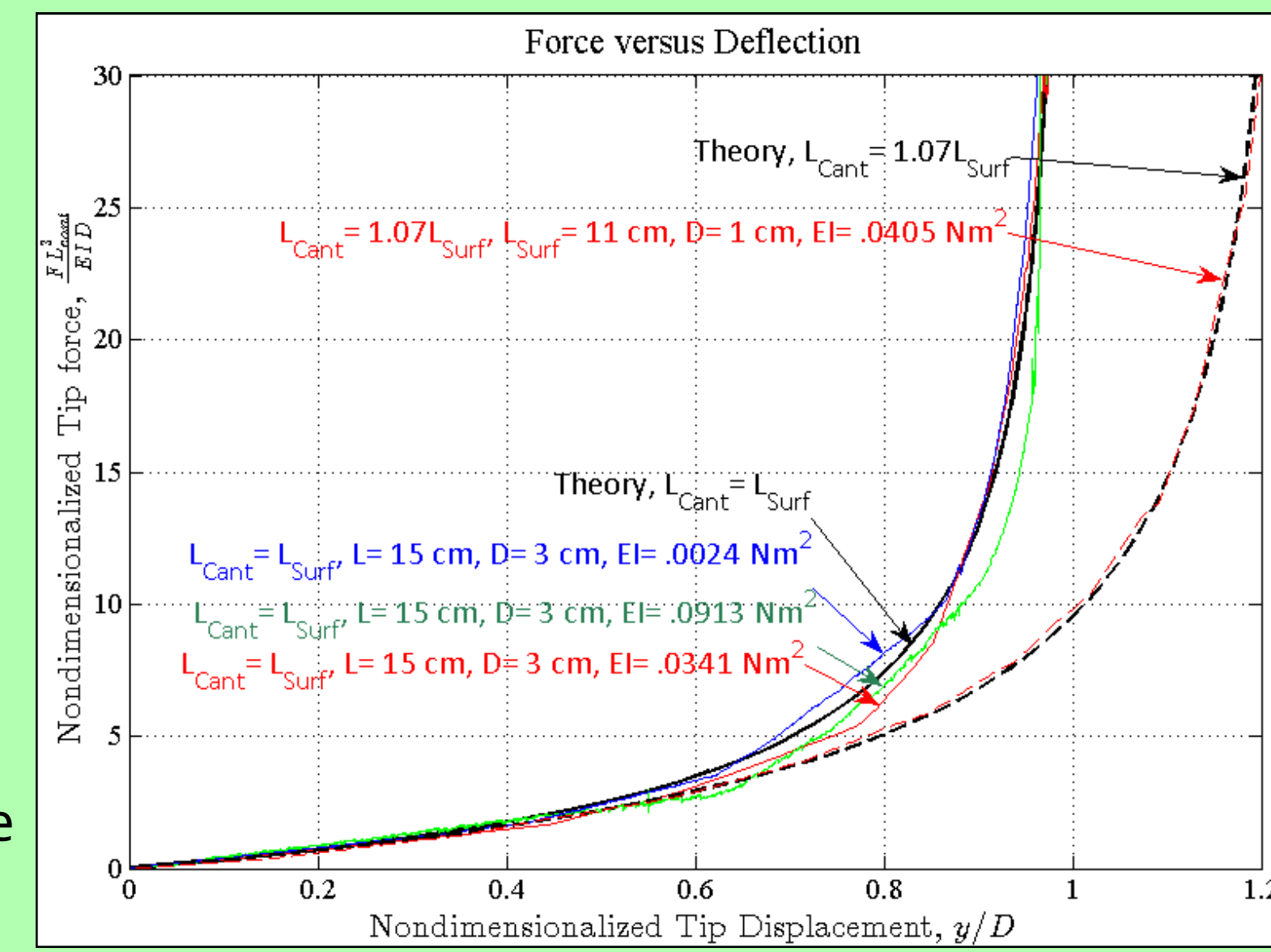
Added $\lambda_{Mech} = 0.06 \text{ Ns/m}$ to all systems



How to implement nonlinear springs?



- A design with essential nonlinearity, low-friction, and one moving part (which increases device lifetime)



Future Work

- Build and test full prototypes with electromagnetic system
- Modify contact-surface stiffening-spring effect to be more volume-compact
- Analytically study stochastic nonlinear dynamics to predict maximum power and robustness
- Apply concepts to utility-scale ocean-wave electricity generation

